

§ 4.6 Variation of Parameters

Introduction: Our goal in this section is to solve linear nonhomogeneous DEs with constant coefficients, where the input function $g(x)$ is not of a form discussed in section 4.4 (linear combinations of sines, cosines, polynomials and $e^{\alpha x}$). Our problem in 4.4 was that we could not find y_p when $g(x)$ was something of the form $\frac{1}{x}$, $\csc x$, $\ln x$, etc.

The method we examine in this section, due to the astronomer and mathematician Joseph Louis Lagrange, is known as **variation of parameters**.

Linear First-Order DEs Revisited:

Recall from section 2.3 Linear First-Order DEs:

$$a_1(x)\frac{dy}{dx} + a_0(x)y = g(x) \rightarrow \frac{dy}{dx} + P(x)y = f(x)$$

Multiplying by the magical function $\mu(x) = e^{\int P(x)dx}$ had a magical effect:

$$e^{\int P(x)dx} \frac{dy}{dx} + e^{\int P(x)dx} P(x)y = e^{\int P(x)dx} f(x) \quad \rightarrow \quad \frac{d}{dx} \left[e^{\int P(x)dx} y \right] = e^{\int P(x)dx} f(x)$$

Then:

$$e^{\int P(x)dx} y = \int e^{\int P(x)dx} f(x) dx + c \quad \rightarrow \quad y = ce^{-\int P(x)dx} + e^{-\int P(x)dx} \int e^{\int P(x)dx} f(x) dx$$

This has the general form that we learned about in 4.1, $y = y_c + y_p$, where

- $y_c = ce^{-\int P(x)dx}$ is a solution of $\frac{dy}{dx} + P(x)y = 0$
- $y_p = e^{-\int P(x)dx} \int e^{\int P(x)dx} f(x) dx$ is a particular solution of $\frac{dy}{dx} + P(x)y = f(x)$

We now try to find y_p a different way, using the method known as **variation of parameters**. The procedure is similar to what we did in section 4.2 (reduction of order).

Suppose we know that y_1 is a solution of $\frac{dy}{dx} + P(x)y = 0$. It can be verified that $y_1 = e^{-\int P(x)dx}$ is a solution, and because the equation is first-order, the general solution is $y = c_1 y_1$.

Variation of Parameters: Try to find a particular solution y_p of the form $y_p = u_1(x)y_1(x)$. We have replaced the constant parameter c_1 with a function $u_1(x)$. Recall, we are trying to find u_1 so that $y_p = u_1(x)y_1(x)$ is a solution. Let's see if we can pull it off.

Substitute $y_p = u_1 y_1$ back into $\frac{dy}{dx} + P(x)y = f(x)$:

Linear Second-Order DEs:

Consider the linear second-order equation: $a_2(x)y'' + a_1(x)y' + a_0(x)y = g(x)$ (1)

In standard form, this is: $y'' + P(x)y' + Q(x)y = f(x)$ (2)

where P , Q , and f are continuous on some interval I .

As we saw in 4.3, we can find the general solution to the associated homogeneous equation of (2) when the coefficients are constant; call it $y_c = c_1 y_1 + c_2 y_2$.

We now ask a question similar to above, can we replace the constants c_1 and c_2 with functions $u_1(x)$ and $u_2(x)$ so that $y_p = u_1 y_1 + u_2 y_2$ is a particular solution of (2)? We need to find those u functions!

Let's take some derivatives and substitute:

$$y'_p = u_1 y'_1 + u'_1 y_1 + u_2 y'_2 + u'_2 y_2$$

$$y''_p = u_1 y''_1 + u'_1 y'_1 + u''_1 y_1 + u'_1 y'_1 + u_2 y''_2 + u'_2 y'_2 + u''_2 y_2 + u'_2 y'_2$$

Substituting into (2) gives:

$$\begin{aligned}
 y_p'' + P(x)y_p' + Q(x)y_p &= \\
 &= u_1y_1'' + 2u_1'y_1' + u_1''y_1 + u_2y_2'' + 2u_2'y_2' + u_2''y_2 + P(x)[u_1y_1' + u_1'y_1 + u_2y_2' + u_2'y_2] + Q(x)[u_1y_1 + u_2y_2] \\
 &= u_1[y_1'' + Py_1' + Qy_1] + u_2[y_2'' + Py_2' + Qy_2] + P[u_1'y_1 + u_1y_1' + u_2'y_2 + u_2y_2'] + u_1''y_1 + u_1'y_1' + u_2''y_2 + u_2'y_2' + u_1'y_1' + u_2'y_2'
 \end{aligned}$$

Since we are trying to find two unknown functions, we need two equations:

By Cramer's Rule, the solution of the system is:

$$u_1' = \frac{W_1}{W} \quad \text{and} \quad u_2' = \frac{W_2}{W}$$

where

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}, \quad W_1 = \begin{vmatrix} 0 & y_2 \\ f(x) & y_2' \end{vmatrix}, \quad W_2 = \begin{vmatrix} y_1 & 0 \\ y_1' & f(x) \end{vmatrix}$$

Then,

$$u_1' = -\frac{y_2 f(x)}{W} \quad \text{and} \quad u_2' = \frac{y_1 f(x)}{W}.$$

Note: W is the Wronskian, and we know that $W(y_1(x), y_2(x)) \neq 0$ for all x in I because

Summary of the Method:

Example: Solve. $y'' - 2y' + y = \frac{e^x}{1+x^2}$

Example: Solve. $2y'' + 18y = 6 \tan(3x)$